Robust Neural Networks Part 4: Intervenability at Inference







Objective Objective of the Tutorial

To discuss methodologies that promote robustness in neural networks at inference

- Part 1: Inference in Neural Networks
- Part 2: Explainability at Inference
- Part 3: Uncertainty at Inference
- Part 4: Intervenability at Inference
 - Definitions of Intervenability
 - Causality
 - Privacy
 - Interpretability
 - Prompting
 - Benchmarking
 - Case Study: Intervenability in Interpretability
- Part 5: Conclusions and Future Directions





Intervenability Through the Causal Glass

Assess: The amenability of neural network decisions to human interventions



"Interventions in data are manipulations that are designed to test for causal factors"

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Schölkopf, B., Locatello, F., Bauer, S., Ke, N. R., Kalchbrenner, N., Goyal, A., & Bengio, Y. (2021). Toward causal representation learning. *Proceedings of the IEEE*, *109*(5), 612-634.



Intervenability Through the Privacy Glass

Assure: The amenability of neural network decisions to human interventions



"Intervenability aims at the possibility for parties involved in any privacy-relevant data processing to interfere with the ongoing or planned data processing"

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[Tutorial@AAAI'24] | [Ghassan AlRegib and Mohit Prabhushankar] | [Feb 21, 2024]

Hansen, M.: Top 10 mistakes in system design from a privacy perspective and privacy protection goals. In: Camenisch, J., Crispo, B., Fischer-Hübner, S., Leenes, R., Russello, G. (eds.) Privacy and Identity Management for Life. IFIP AICT, vol. 375, pp. 14–31. Springer, Heidelberg (2012)





Intervenability

Through the Interpretability Glass

Interpret: The amenability of neural network decisions to human interventions



"The post-hoc field of explainability, that previously only justified decisions, becomes active by being involved in the decision making process and providing limited, but relevant and contextual interventions"

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[Tutorial@AAAI'24] | [Ghassan AlRegib and Mohit Prabhushankar] | [Feb 21, 2024]

AlRegib, Ghassan, and Mohit Prabhushankar. "Explanatory paradigms in neural networks: Towards relevant and contextual explanations." *IEEE Signal Processing Magazine*39.4 (2022): 59-72.





Intervenability

Through the Benchmarking Glass

Verify: The amenability of neural network decisions to human interventions



"... new benchmarks were proposed to specifically test generalization of classification and detection methods with respect to simple algorithmically generated interventions like spatial shifts, blur, changes in brightness or contrast..."

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Schölkopf, B., Locatello, F., Bauer, S., Ke, N. R., Kalchbrenner, N., Goyal, A., & Bengio, Y. (2021). Toward causal representation learning. *Proceedings of the IEEE*, *109*(5), 612-634.



Case Study: Intervenability in Interpretability Challenges in Intervenability

The amenability of neural network decisions to human interventions



- **Assess:** Causality
- **Assure:** Privacy
- **Interpret:** Interpretability
- **Verify: Benchmarking** •

Challenges:

- Choosing the type of Intervention: Explanation **Evaluation**
- Residuals of Interventions: Uncertainty









Case Study: Intervenability in Interpretability Explanation Evaluation

Visual explanations are evaluated via masking the important regions in the image and passing it through the network

Three types of Masking:

- 1. Masking using explanation heatmap
- 2. Pixel-wise masking using explanation as importance
- 3. Structure-wise masking using information encoded in explanation



Masking = Intelligent Intervention



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Case Study: Intervenability in Interpretability Evaluation 1: Explanation Evaluation via Masking

Common evaluation technique is masking the image and checking for prediction correctness

y = PredictionS_x = Explanation masked data

 $E(Y|S_x)$ = Expectation of class given S_x



If across N images, $E(Y|S_{x2}) > E(Y|S_{x1})$, explanation technique 2 is better than explanation technique 1





[Tutorial@AAAI'24] | [Ghassan AlRegib and Mohit Prabhushankar] | [Feb 21, 2024] Chattopadhay, Aditya, et al. "Grad-cam++: Generalized gradient-based visual explanations for deep convolutional networks." 2018 IEEE winter conference on applications of computer vision (WACV). IEEE, 2018.





Evaluation 1: Explanation Evaluation via Masking

However, explanation masking encourages 'larger' explanations

- Larger explanations imply more features in masked images are intact (unmasked)
- This increases likelihood of a correct prediction
- 'Fine-grained' explanations are not promoted







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Case Study: Intervenability in Interpretability Explanation Evaluation

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Pixel-wise Deletion: Sequentially delete (mask) pixels in an image based on their explanation assigned importance scores



Highest importance

Second Highest importance

- •
- •
- .

Least importance

Step 1: Mask highest importance pixel and pass the image through the network. Note the probability of spoonbill.

Step 2: Mask the second highest importance pixel from the image in Step 1 and pass the image through the network. Note the probability of spoonbill.

Step 3: Repeat until all pixels are deleted (masked)



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The removal of the "cause" (important pixels) will force the base model to change its decision.







- Deletion approximates Necessity criterion of a "good" explanation
- AUC for a good explanation will be low
- Deletion encourages finegrained explanations by choosing those heatmaps that select the most relevant pixels





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Pixel-wise Insertion: Sequentially add pixels to a mean image based on their explanation assigned importance scores



Highest importance

- Second Highest importance
 - •
 - •
 - .
- Least importance

Take a mean (grayscale) image

Step 1: Add the highest importance pixel to the mean image and pass it through the network. Note the probability of spoonbill.

Step 2: Add the second highest importance pixel to the image in Step 1 and pass the image through the network. Note the probability of spoonbill.Step 3: Repeat until all pixels are inserted



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The addition of the "cause" (important pixels) will force the base model to change its decision.







Explaining: white stork





AUC=0.929

- Insertion approximates Sufficiency criterion of a "good" explanation
- AUC for a good explanation will be high
- Insertion encourages finegrained explanations by choosing those heatmaps that select the most relevant pixels



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Insertion and Deletion evaluation metrics encourage pixel-wise analysis of explanations













- However, humans do not "see" in pixels
- Rather they view scenes in a "structure-wise" fashion
- While heatmap masking encourages large explanations, pixel-wise masking encourages unrealistic and non-human like explanations





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Case Study: Intervenability in Interpretability Explanation Evaluation

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Evaluation 3: Progressive Structure-wise Insertion and Deletion

Structure-wise Deletion: Sequentially delete (mask) pixels in an image based on the number of bits used to represent the region





Ideal scenario: The explanation encodes the most important information in the least possible bits

CausalCAM in Red¹ GradCAM in Purple GradCAM++ in Green

- *D_C* and *D_G* represent 65% accuracy for CausalCAM and GradCAM respectively
- CausalCAM encodes dense structure-rich features in lesser bits, that aid accuracy



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Evaluation 3: Progressive Structure-wise Insertion and Deletion

Structure-wise Deletion: Sequentially delete (mask) pixels in an image based on the number of bits used to represent the region





Ideal scenario: The explanation encodes the most important information in the least possible bits

Step 1: Choose a threshold in the explanation (say 0.1) and delete (mask) all the pixels in the original image below the threshold. Pass the masked image through the network and note the change in prediction (if any)





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Evaluation 3: Progressive Structure-wise Insertion and Deletion

Structure-wise Deletion: Sequentially delete (mask) pixels in an image based on the number of bits used to represent the region





Y-axis: Performance accuracy across all ratios X-axis: Ratio of Huffman encoded masked and original images for all explanations. Smaller the ratio, less is the number of bits encoding the masked image

Ideal scenario: The explanation encodes the most important information in the least possible bits

Step 1: Choose a threshold in the explanation (say 0.1) and delete (mask) all the pixels in the original image below the threshold. Pass the masked image through the network and note the change in prediction (if any)

Step 2: Calculate the Huffman code for the original and the masked image. The ratio between the codes of masked and original image is taken on the x-axis and the corresponding accuracy across all images is shown on the y-axis



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Step 2: Calculate the Huffman code for the original and the masked image. The ratio between the codes of masked and original image is taken on the x-axis and the corresponding accuracy across all images is shown on the y-axis **Step 3**: Repeat across thresholds

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Evaluation 3: Progressive Structure-wise Insertion and Deletion

Structure-wise Insertion: Sequentially add (insert) pixels in an image based on the number of bits used to represent the region



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CausalCAM in Red¹ GradCAM in Purple GradCAM++ in Green

 CausalCAM encodes dense structure-rich features in at the lowest threshold, that aid accuracy



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Structure-wise insertion and deletion can sometimes promote adversarial explanations





- Best explanations according to structure-wise insertion and deletion.
- Corroborated by high probabilities



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Case Study: Intervenability in Interpretability Pros and Cons

Evaluation 1: Explanation heatmap masking

- **Pro**: Structures are visible in the explanations

Evaluation 2: Pixel-wise insertion and deletion

- **Pro:** Progressively assigns importance to pixels
- **Con**: Encourages large non-fine grained explanations **Con**: Encourages unrealistic and dispersed explanations

Evaluation 3: Structure-wise insertion and deletion

- **Pro**: Encourages structures while progressively assigning importance to structures based on information bits
- **Pro**: Other human-centric measures including SSIM, saliency etc. can be used on x-axis
- **Con**: Encourages causal (and sometimes adversarial) explanations without considering context information ٠





Case Study: Intervenability in Interpretability Challenges in Intervenability

The amenability of neural network decisions to human interventions



- Hence, there is **no single-best** interventional strategy
- Choosing the **right** intervention is still an art

Challenges:

- Choosing the type of Intervention: Explanation **Evaluation**
- Residuals of Interventions: Uncertainty









Case Study: Intervenability in Interpretability Challenges in Intervenability

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VOICE: Variance of Contrastive Explanations for Quantifying Uncertainty in Interpretability



Mohit Prabhushankar, PhD Postdoc



Ghassan AlRegib, PhD Professor







Predictive Uncertainty in Explanations

Explanatory techniques have predictive uncertainty Explanation of Prediction Uncertainty of Explanation



Uncertainty in answering Why Bullmastiff?

Why Bullmastiff?

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Case Study: Intervenability in Interpretability Predictive Uncertainty

Uncertainty due to variance in prediction when model is kept constant



$$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$$

 $\begin{array}{l} y = \mbox{Prediction} \\ V[y] = \mbox{Variance of prediction (Predictive Uncertainty)} \\ S_x = \mbox{Subset of data (Some intervention)} \\ E(Y|S_x) = \mbox{Expectation of class given a subset} \\ V(Y|S_x) = \mbox{Variance of class given all other residuals} \end{array}$





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Case Study: Intervenability in Interpretability Visual Explanations (partially) reduce Predictive Uncertainty

A 'good' explanatory technique is evaluated to have zero $V[E(y|S_x)]$



Key Observation 1: Visual Explanations are evaluated to partially reduce the predictive uncertainty in a neural network

$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$

y = Prediction V[y] = Variance of prediction (Predictive Uncertainty) $S_x = Subset of data (Some intervention)$ $E(Y|S_x) = Expectation of class given a subset$ $V(Y|S_x) = Variance of class given all other residuals$

Network evaluations have nothing to do with human Explainability!

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Predictive Uncertainty in Explanations is the Residual

All other subsets 'not' chosen by the explanatory technique contributes to uncertainty



$$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$$

y = Prediction V[y] = Variance of prediction (Predictive Uncertainty) $S_x =$ Subset of data (Some intervention) $E(Y|S_x) =$ Expectation of class given a subset $V(Y|S_x) =$ Variance of class given all other residuals

Key Observation 2: Uncertainty in Explainability occurs due to all combinations of features that the explanation did not attribute to the network's decision





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Predictive Uncertainty in Explanations is the Residual

All other subsets 'not' chosen by the explanatory technique contributes to uncertainty

$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$

The effect of a chosen Interventions can be measured based on all the Interventions that were not chosen

 $\tilde{E}(Y|S_x) = Expectation of class given a subset$ $V(Y|S_x) = Variance of class given all other residuals$

Key Observation 2: Uncertainty in Explainability occurs due to all combinations of features that the explanation did not attribute to the network's decision

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Predictive Uncertainty in Explanations is the Residual

All other subsets 'not' chosen by the explanatory technique contributes to uncertainty

Snout is not as highlighted as the jowls in explanation (not as important for decision)

Explanation of Prediction Uncertainty of Explanation

However, snout is an important characteristic that is used to differentiate against other dogs. Hence, there is uncertainty on why this feature is not included in the attribution

Key Observation 2: Uncertainty in Explainability occurs due to all combinations of features that the explanation did not attribute to the network's decision





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However, snout is an important characteristic that is used to differentiate against other dogs. Hence, there is uncertainty on why this feature is not included in the attribution

Not chosen features are intractable!





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Quantifying Interventions in Explainability

Contrastive explanations are an intelligent way of obtaining other subsets





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Case Study: Intervenability in Interpretability Quantifying Interventions in Explainability

Uncertainty in Explainability can be used to analyze Explanatory methods and Networks

- Is GradCAM better than GradCAM++?
- Is a SWIN transformer more reliable than VGG-16?

Need objective quantification of Intervention Residuals



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Case Study: Intervenability in Interpretability Quantifying Interventions in Explainability: mIOU

On incorrect predictions, the overlap of explanations and uncertainty is higher



Objective Metric: Intersection over Union (IoU) between explanation and Uncertainty

Higher the IoU, higher the uncertainty in explanation (or less trustworthy is the prediction)

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Case Study: Intervenability in Interpretability Quantifying Interventions in Explainability: SNR

Explanation and uncertainty are dispersed under noise (under low prediction confidence)



Objective Metric: Signal to Noise Ratio of the Uncertainty map

Higher the SNR of uncertainty, more is the dispersal (or less trustworthy is the prediction)





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Case Study: Intervenability in Interpretability Quantifying Interventions in Explainability: mIOU

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Case Study: Intervenability in Interpretability Quantifying Interventions in Explainability: mIOU

On incorrect predictions, the overlap of explanations and uncertainty is higher



Objective Metric 1: Intersection over Union (IoU) between explanation and Uncertainty

Higher the IoU, higher the uncertainty in explanation (or less trustworthy is the prediction)

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Case Study: Intervenability in Interpretability Quantifying Interventions in Explainability: SNR

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Case Study: Intervenability in Interpretability Challenges in Intervenability

The amenability of neural network decisions to human interventions



- Not choosing interventions causes ٠ uncertainty in the chosen interventions
- **Residuals** must be **analyzed** intelligently to 'trust or not to trust' predictions at inference
- Gradients quantify residual uncertainty

Challenges:

- Choosing the type of Intervention: Explanation **Evaluation**
- Residuals of Interventions: Uncertainty









Intervenability Through the Human Glass

The amenability of neural network decisions to human interventions



- Assess: Causality
- Assure: Privacy
- Interpret: Interpretability
- Actuate: Prompting
- Verify: Benchmarking

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Detection and Localization

CURE-TSD: Challenging Unreal and Real Environments for Traffic Sign Detection

Data Characteristics:

- 49 real and virtual sequences
- 300 frames in each sequence
- 12 different challenges including decolorization, codec error, lens blur etc.
- 5 progressively increasingly levels in each challenge
- Goal: Detect and localize traffic signs





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Temel, Dogancan, et al. "Cure-tsd: Challenging unreal and real environments for traffic sign detection." *IEEE Transactions on Intelligent Transportation Systems* (2017).

Recognition

CURE-TSR: Challenging Unreal and Real Environments for Traffic Sign Recognition

Data Characteristics:

- 2 million real and virtual traffic sign images
- 14 Traffic signs including common signs like stop, no-right, no-left etc. and uncommon signs like goods-vehicles, priority lanes etc.
- 12 different challenges including decolorization, codec error, lens blur etc.
- 5 progressively increasingly levels in each challenge





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D. Temel, G. Kwon*, M. Prabhushankar*, and G. AlRegib, "CURE-TSR: Challenging unreal and real environments for traffic sign recognition," in Neural Information Processing Systems (NIPS) Workshop on Machine Learning for Intelligent Transportation Systems, Long Beach, U.S., December 2017, (*: equal contribution)

Recognition

ImageNet-C: ImageNet-Corruptions

Gaussian Noise

Shot Noise

Data Characteristics:

- 3.75 million images
- 15 different challenges including decolorization, codec error, lens blur etc. for testing
- 4 different challenges for validation and training
- 5 progressively increasingly levels in each challenge
- Goal: Recognize 1000 classes from ImageNet using pretrained networks





Impulse Noise



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Defocus Blur Frosted Glass Blur

Hendrycks, Dan, and Thomas Dietterich. "Benchmarking neural network robustness to common corruptions and perturbations." *arXiv preprint arXiv:1903.12261* (2019).

Recognition

ImageNet-P: ImageNet-Perturbations

Data Characteristics:

- 5 million images
- 100 perturbations of 50000 images
- 10 frames of algorithmically generated perturbations for each image in ImageNet validation testset
- 10 common perturbations including brightness, tilt, motion etc.





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Retrieval and Recognition

CURE-OR: Challenging Unreal and Real Environments for Object Recognition

Data Characteristics:

- 1 million images
- 100 common household objects and 10000 images per object
- 5 backgrounds, 5 object orientations, 5 devices, and 78 challenging conditions
- Goal: To recognize and retrieve the same object across backgrounds, orientations, devices, and challenging conditions





Challenge Type: None





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D. Temel*, J. Lee*, and G. AlRegib, "CURE-OR: Challenging unreal and real environments for object recognition," IEEE International Conference on Machine Learning and Applications, Orlando, Florida, USA, December 2018, (*: equal contribution)



